

TIME SERIES ANALYSIS IN SOCIOPHYSICS AND ECONOPHYSICS

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Time Series

Series of numbers (X_t)

$$X_1, X_2, X_3, \dots, X_N$$

Mean value

$$\langle X \rangle = \frac{1}{N} \sum_{i=1}^N X_i$$

n -th moment

$$\langle X^n \rangle = \frac{1}{N} \sum_{i=1}^N X_i^n$$

Variance

$$\text{Var}(X) = \frac{1}{N} \sum_{i=1}^N (X_i - \langle X \rangle)^2$$

$$\text{Var}(X) = \frac{1}{N} \sum_{i=1}^N X_i^2 - 2\langle X \rangle \frac{1}{N} \sum_{i=1}^N X_i + \langle X \rangle^2 = \langle X^2 \rangle - \langle X \rangle^2$$

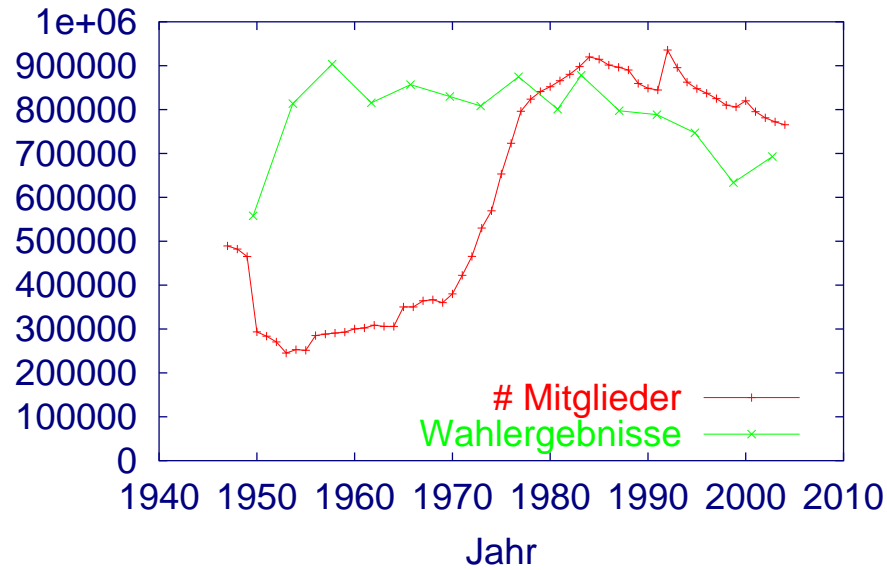
Standard deviation: $\text{std}(X) = \sqrt{\text{Var}(X)}$

Taking into account recency of the values

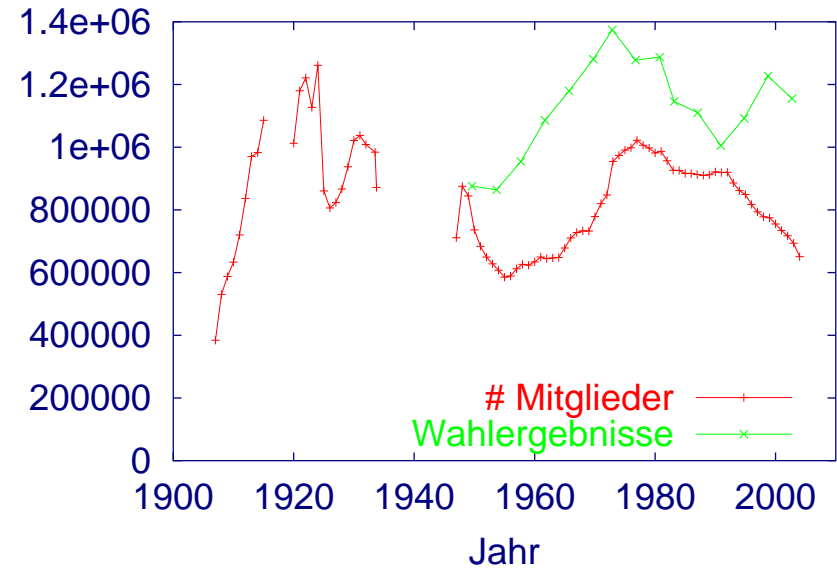
$$\langle X \rangle_1 = X_1, \langle X \rangle_t = \alpha X_t + (1 - \alpha) \langle X \rangle_{t-1}$$

Problems with Real Data

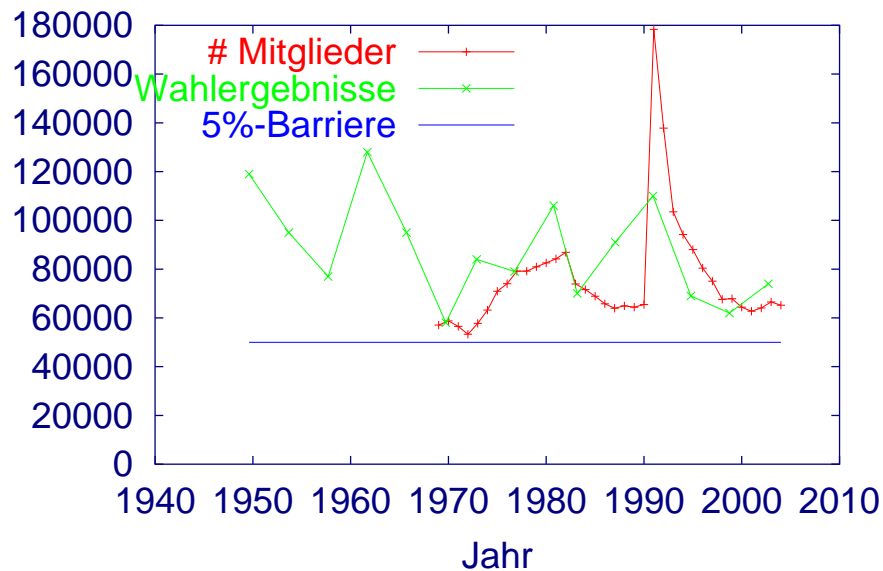
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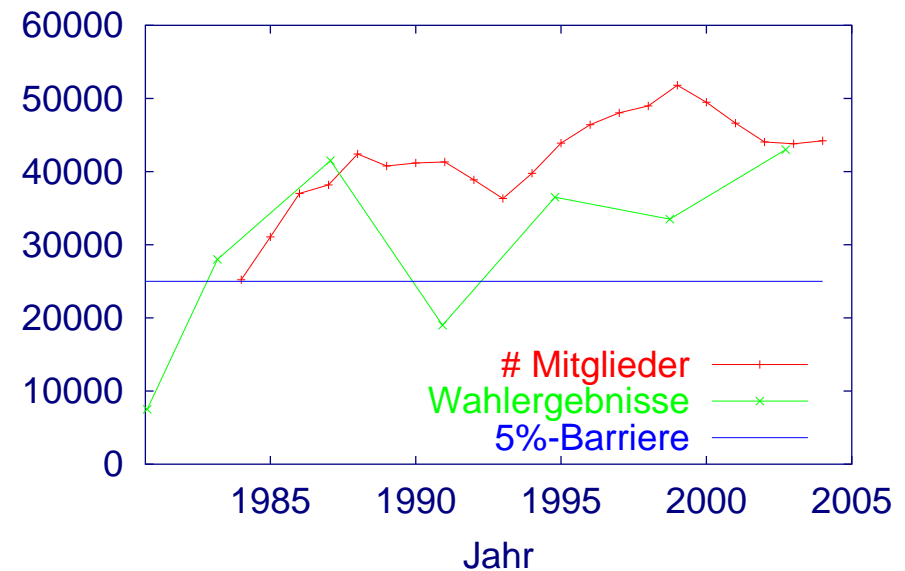
SPD



FDP



Gruene



Wegscheider Trend Analysis

t	1	2	3	4	5	6	7	8	9	10	11	12
A_t	2	1	1	6	5	9	8	4	5	5	5	2
	2	—	1	6	5	9	8	4	—	—	5	2
p_t	—	0	—	—	—	—	—	—	0	0	—	—

Wegscheider Trend Analysis

t	1	2	3	4	5	6	7	8	9	10	11	12
A_t	2	1	1	6	5	9	8	4	5	5	5	2
	2	–	1	6	5	9	8	4	–	–	5	2
	2	–	1	6	5	9	–	4	–	–	5	2
p_t	–	0	–	–	–	–	0	–	0	0	–	–

Wegscheider Trend Analysis

t	1	2	3	4	5	6	7	8	9	10	11	12
A_t	2	1	1	6	5	9	8	4	5	5	5	2
	2	—	1	6	5	9	8	4	—	—	5	2
	2	—	1	6	5	9	—	4	—	—	5	2
	—	—	1	6	5	9	—	4	—	—	5	2
p_t	-1	0	—	—	—	—	0	—	0	0	—	—

Wegscheider Trend Analysis

t	1	2	3	4	5	6	7	8	9	10	11	12
A_t	2	1	1	6	5	9	8	4	5	5	5	2
	2	—	1	6	5	9	8	4	—	—	5	2
	2	—	1	6	5	9	—	4	—	—	5	2
	—	—	1	6	5	9	—	4	—	—	5	2
	—	—	1	—	—	9	—	4	—	—	5	2
p_t	-1	0	—	-1	1	—	0	—	0	0	—	—

Wegscheider Trend Analysis

t	1	2	3	4	5	6	7	8	9	10	11	12
A_t	2	1	1	6	5	9	8	4	5	5	5	2
	2	—	1	6	5	9	8	4	—	—	5	2
	2	—	1	6	5	9	—	4	—	—	5	2
	—	—	1	6	5	9	—	4	—	—	5	2
	—	—	1	—	—	9	—	4	—	—	5	2
	—	—	1	—	—	9	—	—	—	—	—	2
p_t	-1	0	—	-1	1	—	0	1	0	0	-1	—

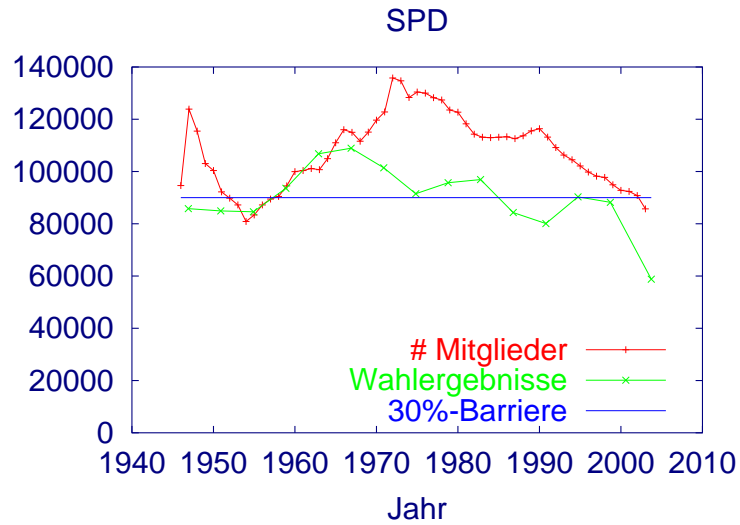
Wegscheider Trend Analysis

t	1	2	3	4	5	6	7	8	9	10	11	12
A_t	2	1	1	6	5	9	8	4	5	5	5	2
	2	—	1	6	5	9	8	4	—	—	5	2
	2	—	1	6	5	9	—	4	—	—	5	2
	—	—	1	6	5	9	—	4	—	—	5	2
	—	—	1	—	—	9	—	4	—	—	5	2
	—	—	1	—	—	9	—	—	—	—	—	2
	—	—	1	—	—	9	—	—	—	—	—	—
p_t	-1	0	—	-1	1	—	0	1	0	0	-1	-7

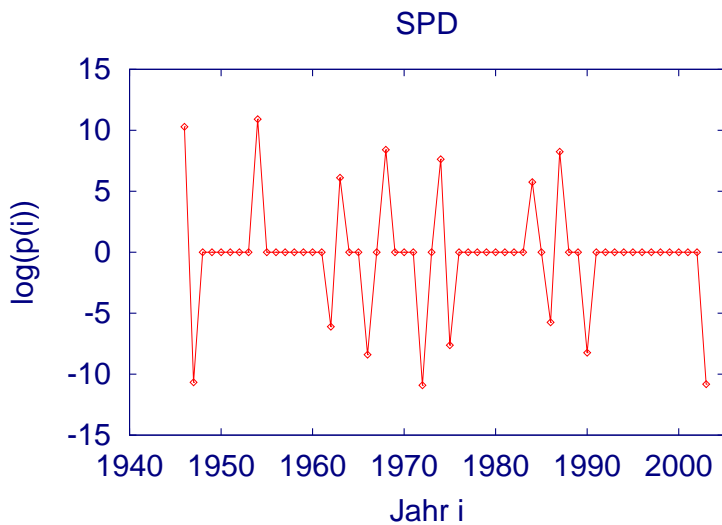
Wegscheider Trend Analysis

t	1	2	3	4	5	6	7	8	9	10	11	12
A_t	2	1	1	6	5	9	8	4	5	5	5	2
	2	—	1	6	5	9	8	4	—	—	5	2
	2	—	1	6	5	9	—	4	—	—	5	2
	—	—	1	6	5	9	—	4	—	—	5	2
	—	—	1	—	—	9	—	4	—	—	5	2
	—	—	1	—	—	9	—	—	—	—	—	2
	—	—	1	—	—	9	—	—	—	—	—	—
	—	—	—	—	—	—	—	—	—	—	—	—
p_t	-1	0	8	-1	1	-8	0	1	0	0	-1	-7

Trend Reversals for Bavarian SPD



28,2% (1954) – 31,2% (1958) – 35,6% (1962)
 31,2% (1958) – 35,6% (1962) – 36,3% (1966)
 36,3% (1966) – 33,8% (1970) – 30,5% (1974)
 30,5% (1974) – 31,9% (1978) – 32,3% (1982)
 32,3% (1982) – 28,1% (1986) – 26,7% (1990)



1962 negative, 1963 positive
 1966 negative, 1968 positive
 1974 positive, 1975 negative
 1984 positive
 1990 negative

Covariance between two time series

two time series: $(A_i) : A_1, A_2, \dots, A_X$

$(B_i) : B_1, B_2, \dots, B_X$

Covariance:

$$\text{Cov}(A, B) = \langle A \cdot B \rangle - \langle A \rangle \cdot \langle B \rangle = \frac{1}{X} \sum_{i=1}^X A_i \cdot B_i - \frac{1}{X} \sum_{i=1}^X A_i \cdot \frac{1}{X} \sum_{i=1}^X B_i$$

Correlation:

$$\rho(A, B) = \frac{\text{Cov}(A, B)}{\sqrt{\text{Var}(A) \cdot \text{Var}(B)}}$$

Correlation is restricted to the interval $[-1; 1]$.

Can Election Results be Predicted by Opinion Polls?

Crosscorrelations

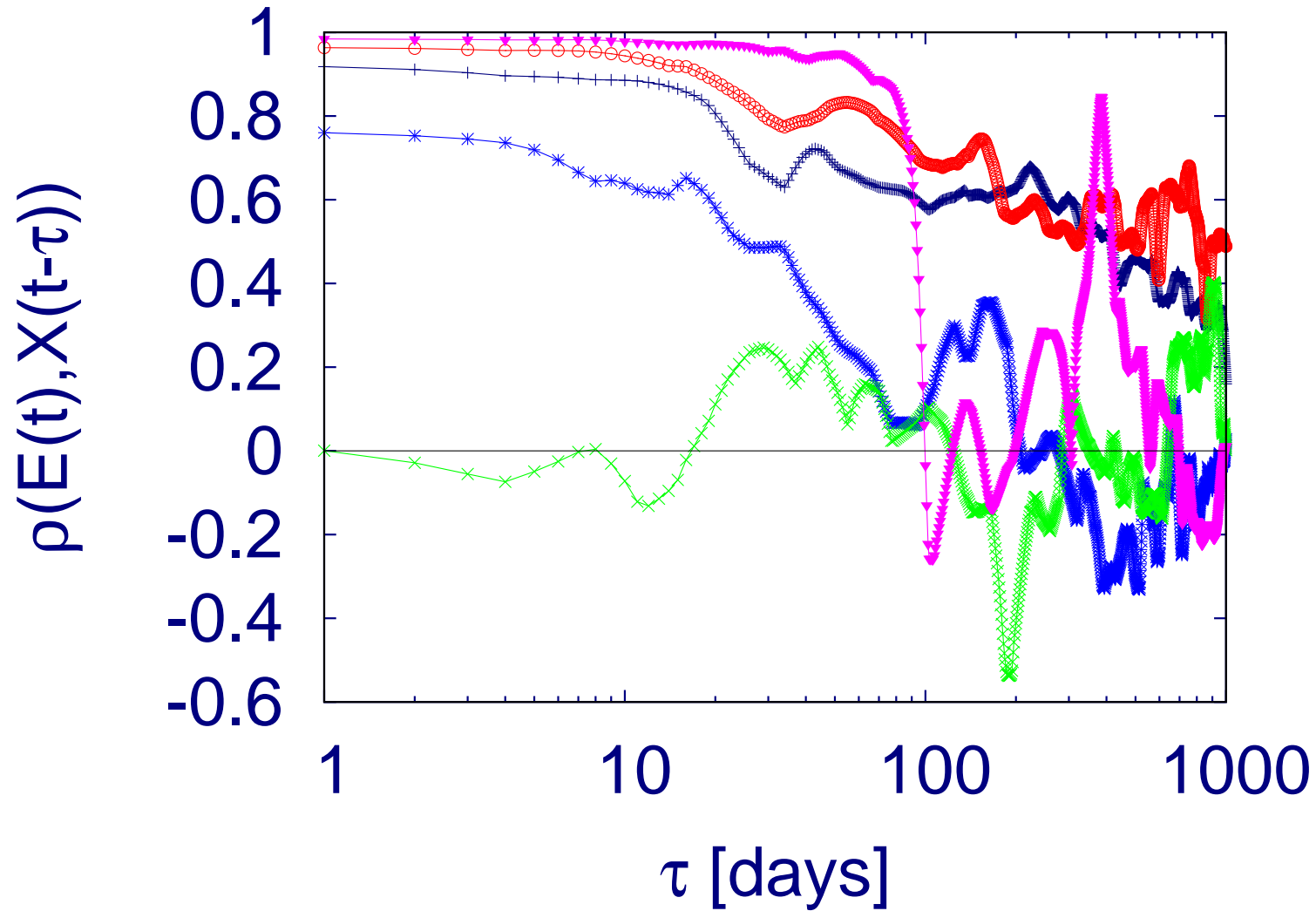
time series ($E(t)$) of election results

time series ($X(t)$) of poll results

crosscorrelation $\rho_\tau = \rho(E(t), X(t - \tau))$

$$\rho_\tau = \frac{\langle E(t) \times X(t - \tau) \rangle - \langle E(t) \rangle \times \langle X(t - \tau) \rangle}{\sqrt{\text{Var}(E(t)) \times \text{Var}(X(t - \tau))}}$$

Crosscorrelations between Election Results and Poll Results



Be careful with correlations

Example: (X_t)	-2	-1	0	1	2
(Y_t)	4	1	0	1	4

$$\rho(X, Y) = 0, \text{ but } Y_t = X_t^2$$

External influences on time series

Bavaria of the 19th century: correlation between numbers of monks and of babies

Partial Correlations

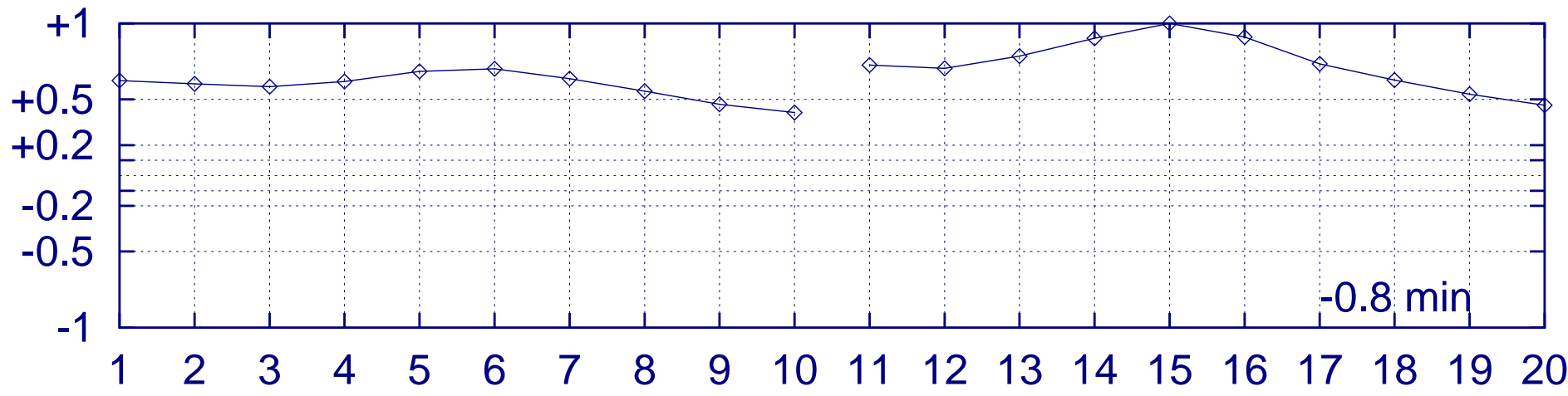
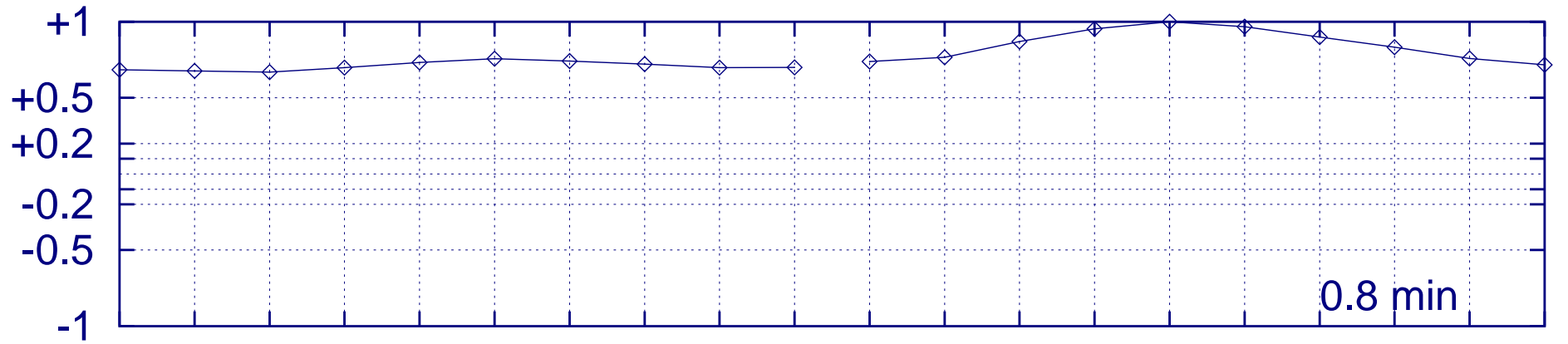
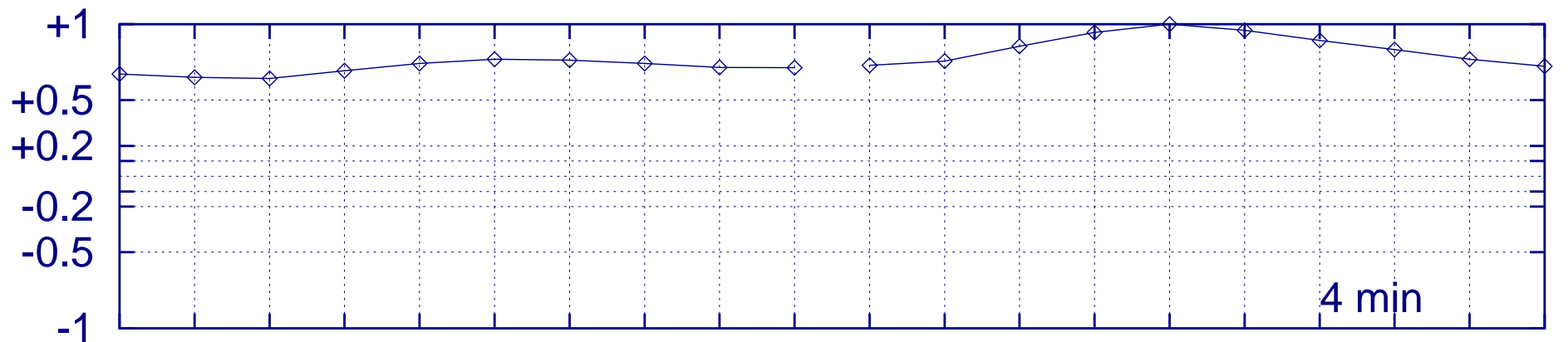
Correlation matrix between two sets \mathcal{X} and \mathcal{Y} of observables

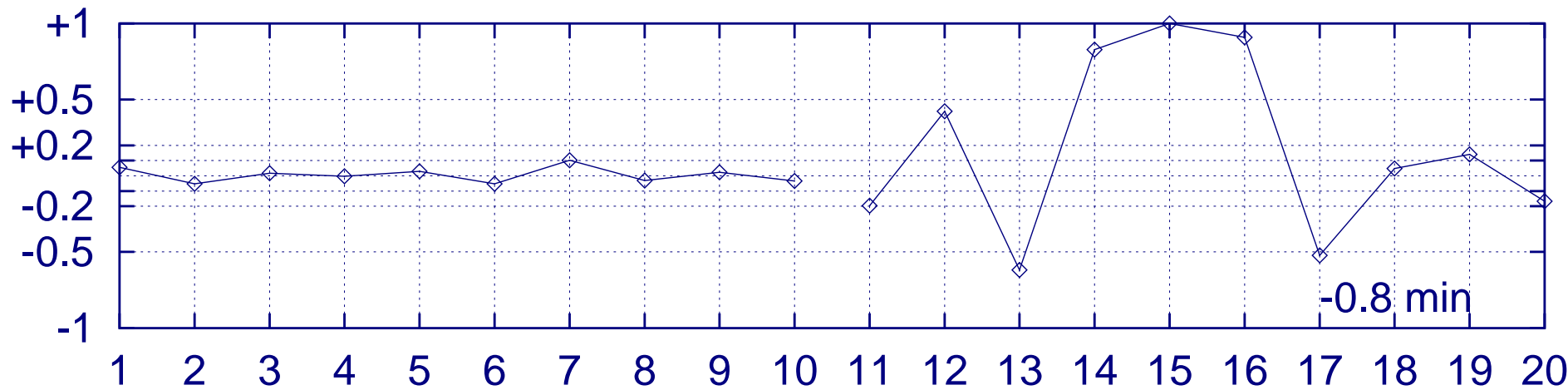
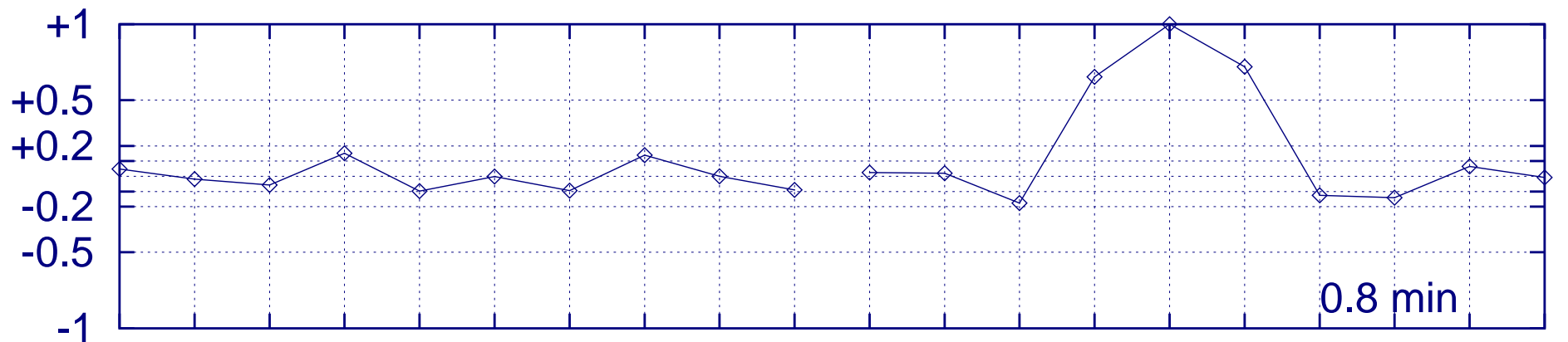
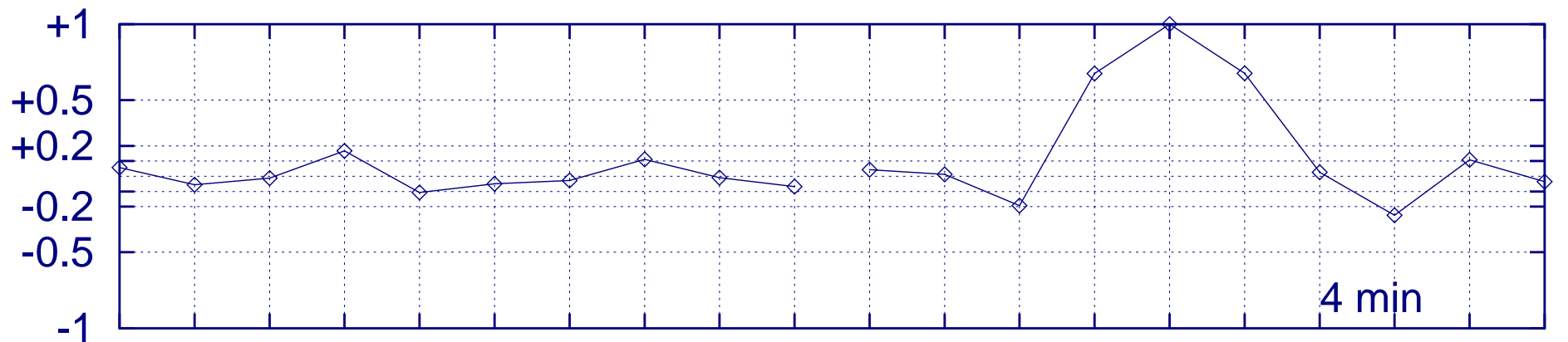
$$\varrho(\mathcal{X}, \mathcal{Y}) = \begin{pmatrix} \varrho(X_1, Y_1) & \dots & \varrho(X_1, Y_m) \\ \vdots & \vdots & \vdots \\ \varrho(X_n, Y_1) & \dots & \varrho(X_n, Y_m) \end{pmatrix}$$

$$\varrho(X, Y|\mathcal{Z}) = \frac{\varrho(X, Y) - \varrho(X, \mathcal{Z}) \cdot \varrho^{-1}(\mathcal{Z}, \mathcal{Z}) \cdot \varrho(\mathcal{Z}, Y)}{\sqrt{(1 - \varrho(X, \mathcal{Z}) \cdot \varrho^{-1}(\mathcal{Z}, \mathcal{Z}) \cdot \varrho(\mathcal{Z}, X)) \text{ (same for } Y\text{)}}}$$

If $\mathcal{Z} = \{Z\}$:

$$\varrho(X, Y|Z) = \frac{\varrho(X, Y) - \varrho(X, Z)\varrho(Y, Z)}{\sqrt{(1 - \varrho^2(X, Z))(1 - \varrho^2(Y, Z))}}$$





Autocorrelations

one time series $(X_t) : X_1, X_2, X_3, \dots, X_N$

Define a new time series (Y_t) by shifting (X_t) by a time lag τ :

$$(Y_i := X_{i+\tau}), \quad 1 \leq i \leq N - \tau$$

Autocorrelation

$$\rho_\tau = \frac{\langle X(0)X(\tau) \rangle - \langle X(0) \rangle \langle X(\tau) \rangle}{\sqrt{\text{Var}(X(0))\text{Var}(X(\tau))}}$$

with the restricted time series

$$(X(\tau)_i) : X_{1+\tau}, X_{2+\tau}, X_{3+\tau}, \dots, X_{N-\tau_{\max}+\tau}$$

Autocorrelation is invariant against time reversal

Stationary Time Series

Weak condition:

Mean value and variance of a time series are constant.

Then formulas can be simplified:

$$\rho_{\tau} = \frac{\langle X(0)X(\tau) \rangle - \langle X(0) \rangle^2}{\text{Var}(X(0))}$$

But usually these time series are not stationary.

Theory of Autoregressive Processes

Autoregressive process of order p

$$X_t = \alpha_1 X_{t-1} + \alpha_2 X_{t-2} + \dots + \alpha_p X_{t-p} + \varepsilon_t$$

with white noise ε_t

$$\begin{aligned} \langle X(t)X(t-\tau) \rangle &= \alpha_1 \langle X(t-1)X(t-\tau) \rangle + \dots \\ &+ \alpha_p \langle X(t-p)X(t-\tau) \rangle \\ &+ \langle \varepsilon(t)X(t-\tau) \rangle \\ \langle X(t) \rangle \langle X(t-\tau) \rangle &= \alpha_1 \langle X(t-1) \rangle \langle X(t-\tau) \rangle + \dots \\ &+ \alpha_p \langle X(t-p) \rangle \langle X(t-\tau) \rangle \\ &+ \langle \varepsilon(t) \rangle \langle X(t-\tau) \rangle \end{aligned}$$

Assuming stationarity, one gets Yule-Walker-Equations:

$$\varrho_1 = \alpha_1 \varrho_0 + \alpha_2 \varrho_1 + \dots + \alpha_p \varrho_{p-1}$$

$$\varrho_2 = \alpha_1 \varrho_1 + \alpha_2 \varrho_0 + \dots + \alpha_p \varrho_{p-2}$$

...

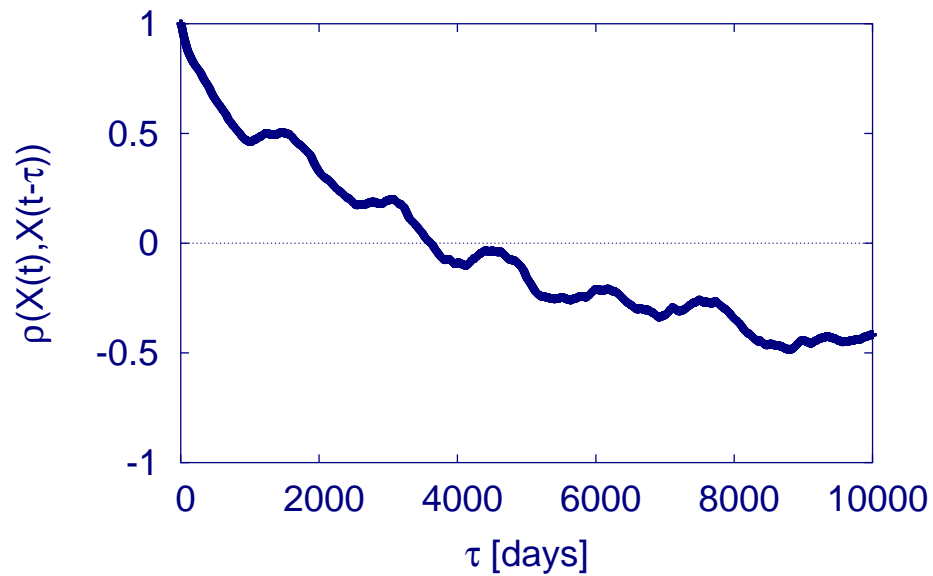
$$\varrho_p = \alpha_1 \varrho_{p-1} + \alpha_2 \varrho_{p-2} + \dots + \alpha_p \varrho_0$$

Example: $p = 1$ (Markov process)

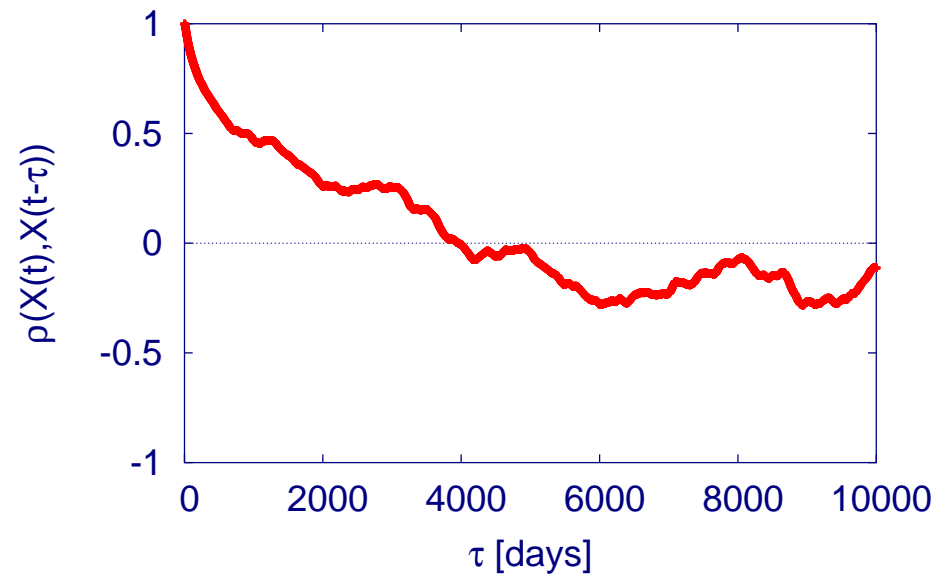
$$\varrho_1 = \alpha_1, \quad \varrho_\tau = \alpha_1^\tau \quad \forall \tau > 0$$

Do we see this exponential behavior?

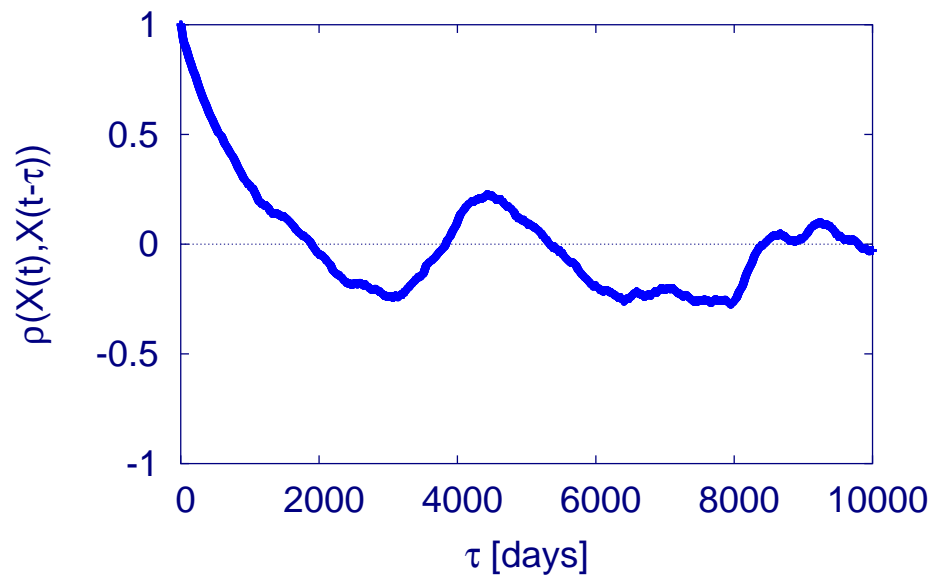
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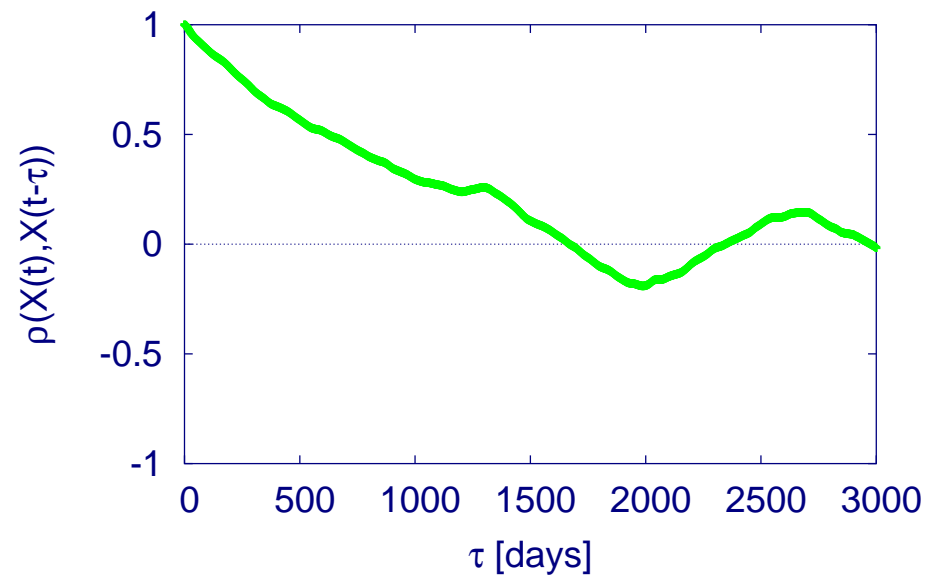
SPD



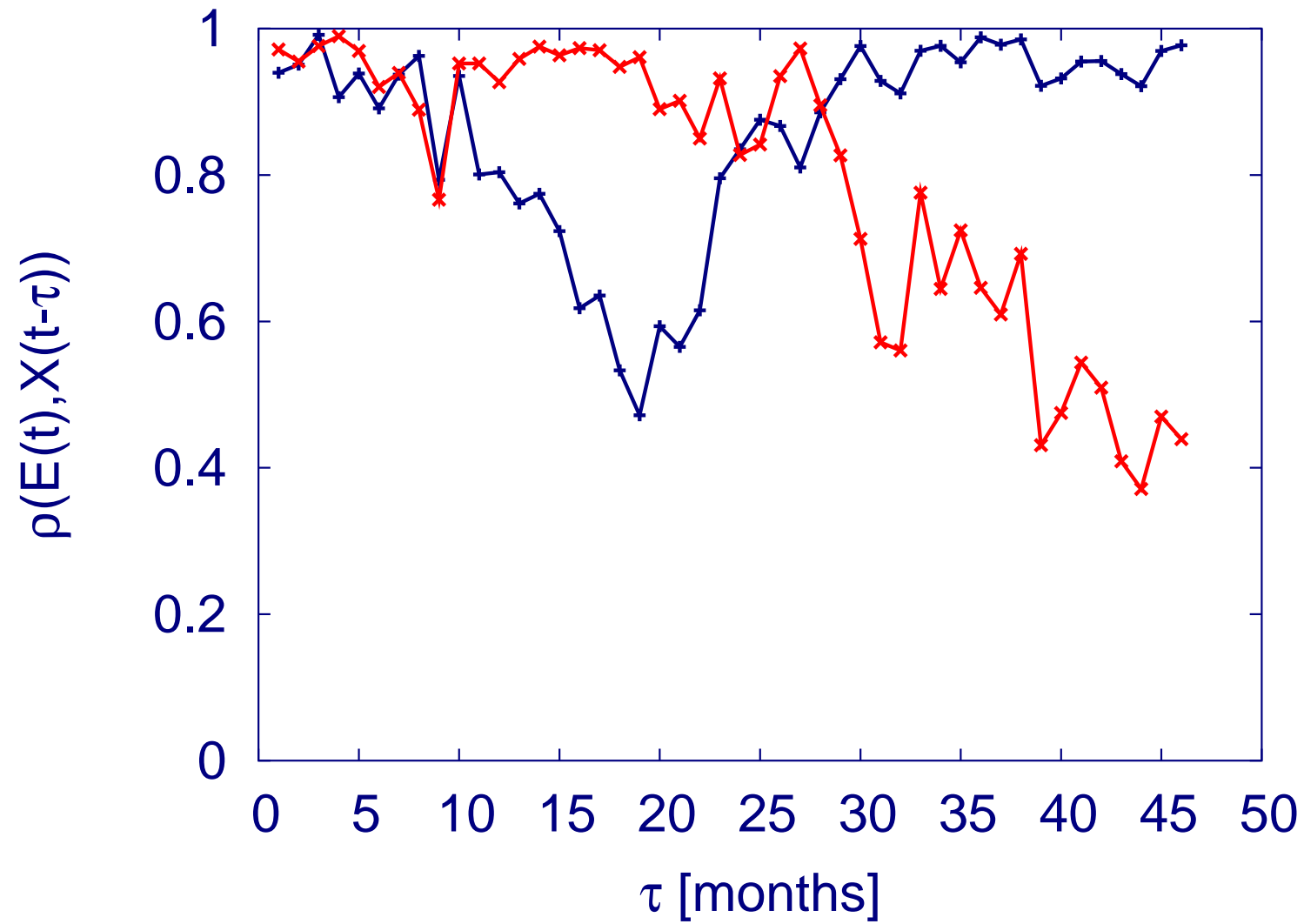
FDP



GRU



Great Britain: Tories and Labour



Theory of Autoregressive Processes

Which value does the order p take?

Let us assume, the order is k :

$$Q_{\tau} = \Phi_{k1} Q_{\tau-1} + \dots + \Phi_{kk} Q_{\tau-k}$$

$$Y_k \vec{\Phi}_k = \vec{Q}$$

Resolve for Φ_{kk} :

$$\Phi_{kk} = \begin{array}{c} \left| \begin{array}{ccccc} 1 & \varrho_1 & \dots & \varrho_{k-2} & \varrho_1 \\ \varrho_1 & 1 & \dots & \varrho_{k-3} & \varrho_2 \\ \varrho_2 & \varrho_1 & \dots & \varrho_{k-4} & \varrho_3 \\ \vdots & & \ddots & & \vdots \\ \varrho_{k-1} & \varrho_{k-2} & \dots & \varrho_1 & \varrho_k \end{array} \right| \\ \hline \left| \begin{array}{ccccc} 1 & \varrho_1 & \dots & \varrho_{k-2} & \varrho_{k-1} \\ \varrho_1 & 1 & \dots & \varrho_{k-3} & \varrho_{k-2} \\ \varrho_2 & \varrho_1 & \ddots & \varrho_{k-4} & \varrho_{k-3} \\ \vdots & & \ddots & & \vdots \\ \varrho_{k-1} & \varrho_{k-2} & \dots & \varrho_1 & 1 \end{array} \right| \end{array}$$

If $\Phi_{kk} = 0$ then $k > p$.