

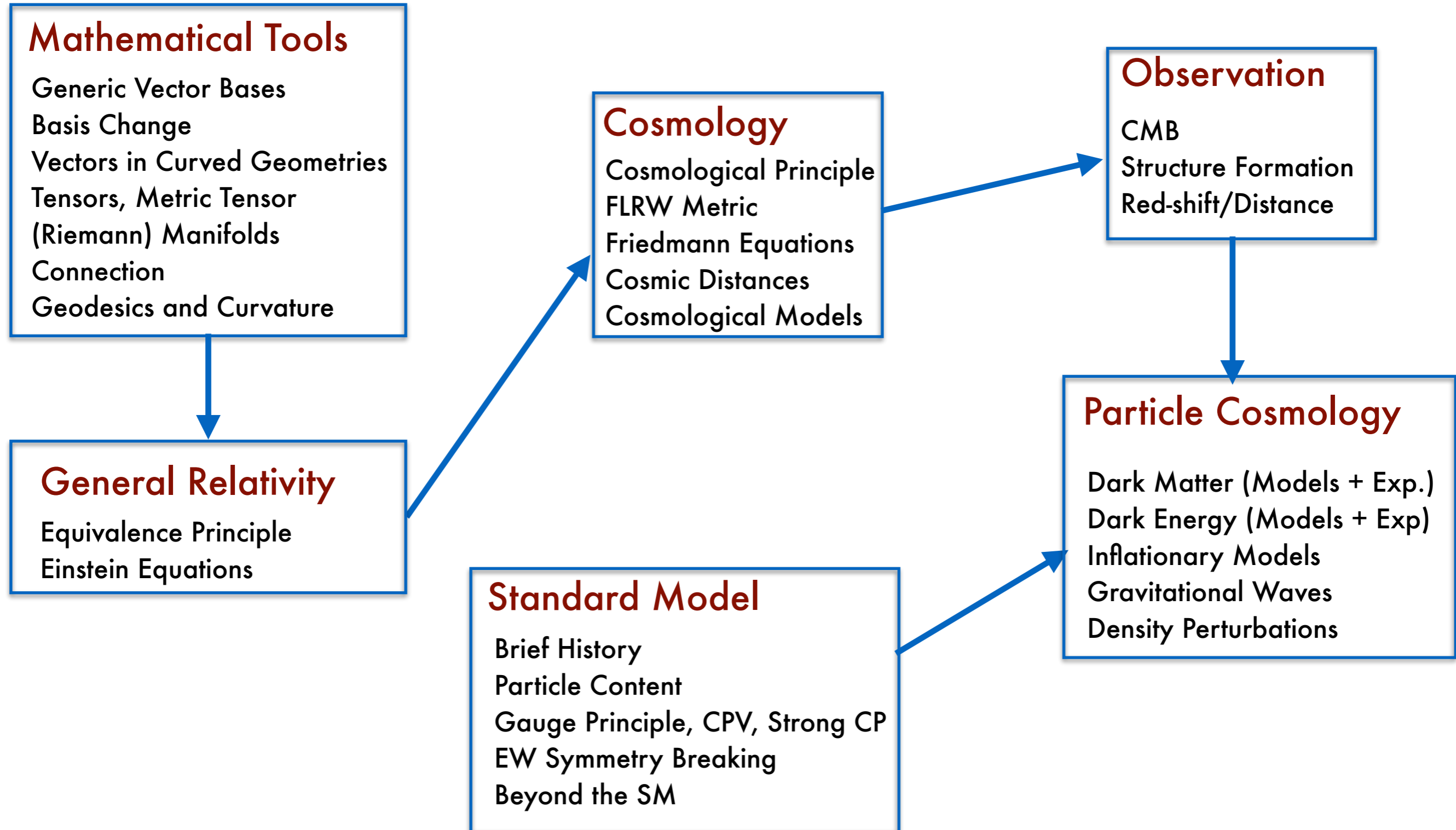
Introductory Particle Cosmology

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Lecture 2



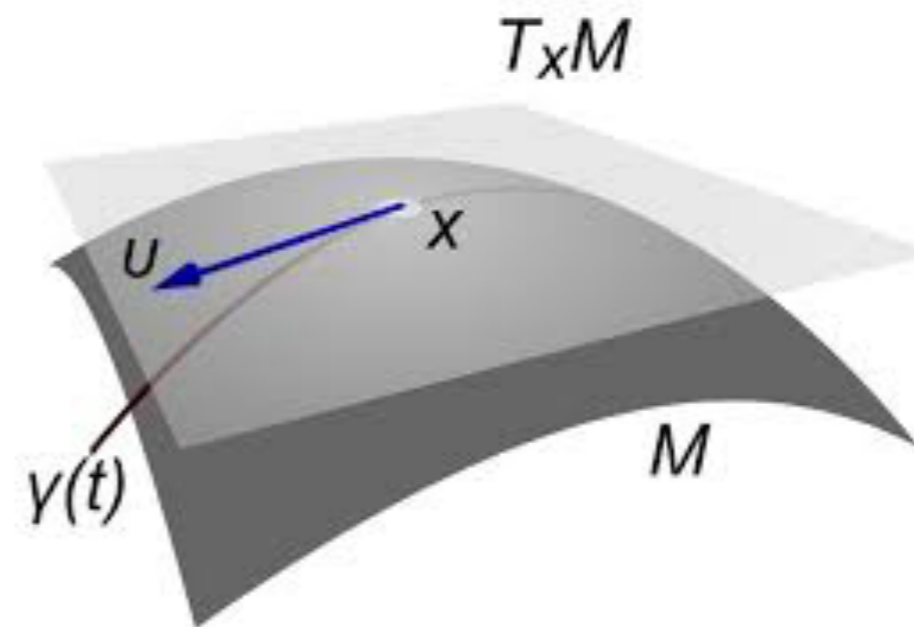
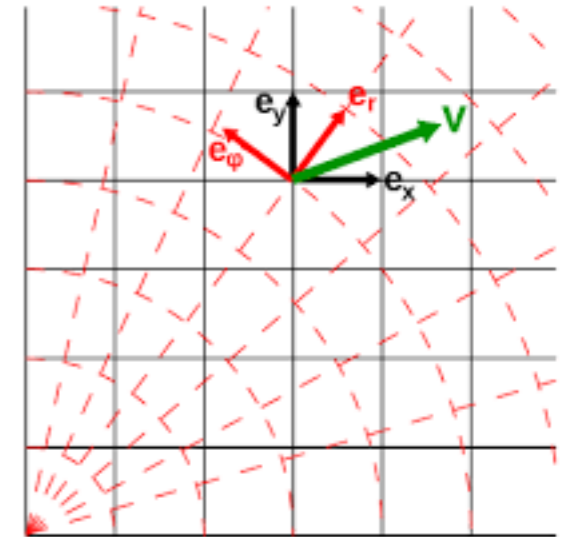
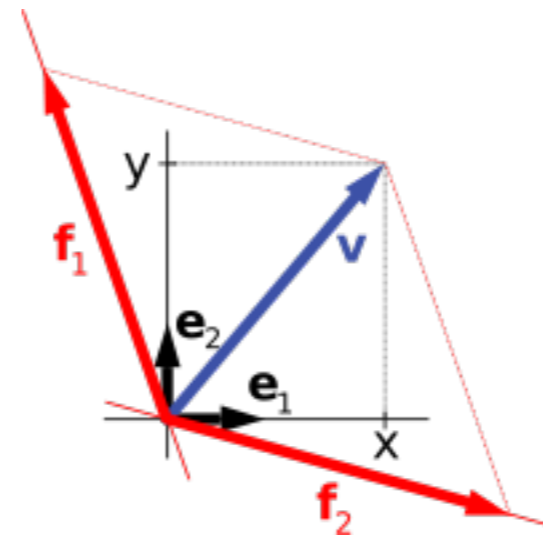
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1 Di, 17. Apr. 2018	10:00	12:00	05 119 Minkowski-Raum
2 Do, 19. Apr. 2018	08:00	10:00	05 119 Minkowski-Raum
3 Di, 24. Apr. 2018	10:00	12:00	05 119 Minkowski-Raum
4 Do, 26. Apr. 2018	08:00	10:00	05 119 Minkowski-Raum
5 Do, 3. Mai 2018	08:00	10:00	05 119 Minkowski-Raum
6 Di, 8. Mai 2018	10:00	12:00	05 119 Minkowski-Raum
7 Di, 15. Mai 2018	10:00	12:00	05 119 Minkowski-Raum
8 Do, 17. Mai 2018	08:00	10:00	05 119 Minkowski-Raum
9 Di, 22. Mai 2018	10:00	12:00	05 119 Minkowski-Raum
10 Do, 24. Mai 2018	08:00	10:00	05 119 Minkowski-Raum
11 Di, 29. Mai 2018	10:00	12:00	05 119 Minkowski-Raum
12 Di, 5. Jun. 2018	10:00	12:00	05 119 Minkowski-Raum
13 Do, 7. Jun. 2018	08:00	10:00	05 119 Minkowski-Raum
14 Di, 12. Jun. 2018	10:00	12:00	05 119 Minkowski-Raum
15 Do, 14. Jun. 2018	08:00	10:00	05 119 Minkowski-Raum
16 Di, 19. Jun. 2018	10:00	12:00	05 119 Minkowski-Raum
17 Do, 21. Jun. 2018	08:00	10:00	05 119 Minkowski-Raum
18 Di, 26. Jun. 2018	10:00	12:00	05 119 Minkowski-Raum
19 Do, 28. Jun. 2018	08:00	10:00	05 119 Minkowski-Raum
20 Di, 3. Jul. 2018	10:00	12:00	05 119 Minkowski-Raum
21 Do, 5. Jul. 2018	08:00	10:00	05 119 Minkowski-Raum



H. Minkowski
(1864-1909)

Physics Dept. Building, 5th Floor

Vector Spaces
 (Ortho-normal) bases
 Change of Basis
 Non-orthonormal bases
 Covariant and contravariant vectors
 Tensors
 Curved Spaces
 Vectors on curved spaces
 Covariant Differentiation
 Geodetics
 Curvature



Covariance and Contravariance

See notes

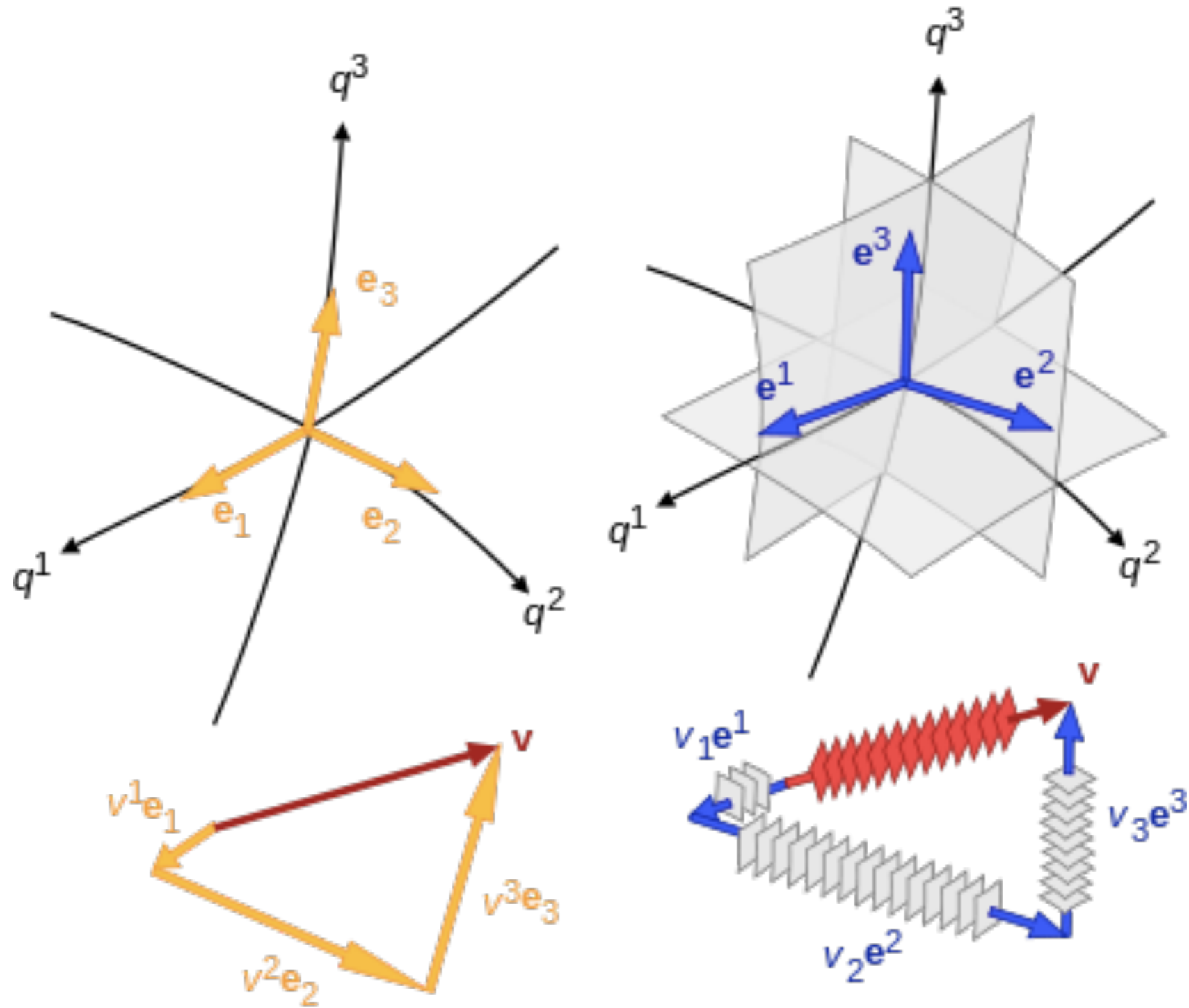


Figure from wikipedia

Stress Tensor

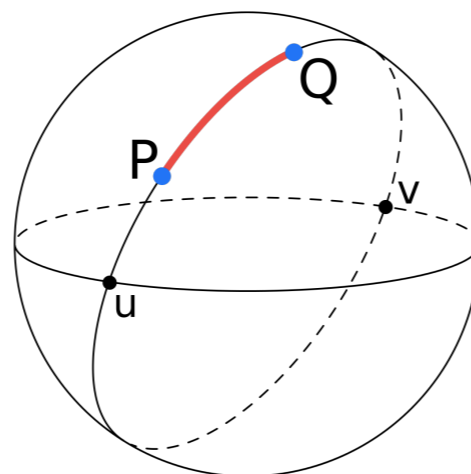
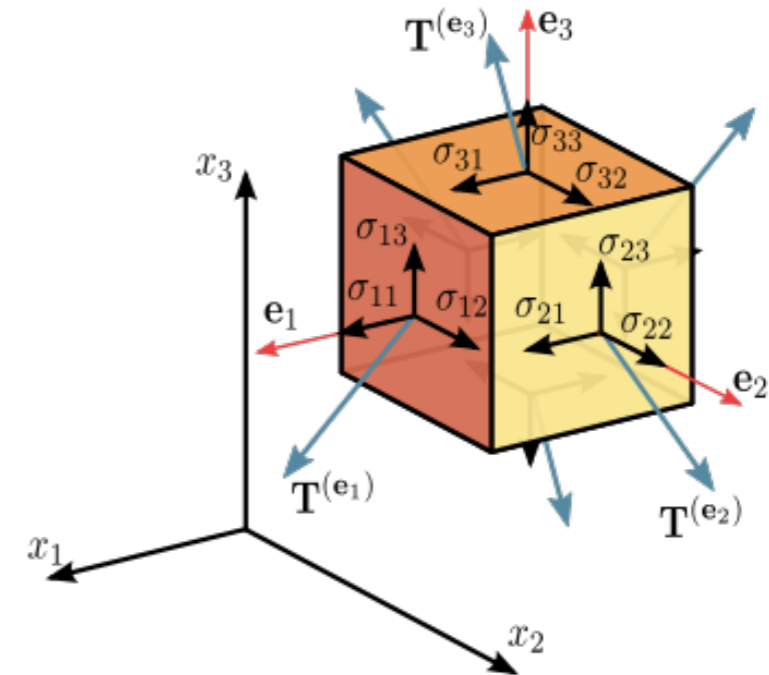
$$T_i = \sigma_{ij}n_j$$

T= stress vector

n= normal to the plane to decompose on **e_i**

Inertial momentum tensor

$$L_i = I_{ij}\omega_j$$



Metric tensor

$$dl^2 = g_{ij}dx^i dx^j$$

Contravariant $v'^{\mu'} = \frac{\partial x'^{\mu'}}{\partial x^{\mu}} v^{\mu}$

Covariant $v'_{\mu'} = \frac{\partial x^{\mu}}{\partial x'^{\mu'}} v_{\mu}$

Tensor with two covariant indices $X'_{\alpha\beta} = \frac{\partial x^{\gamma}}{\partial x'^{\alpha}} \frac{\partial x^{\delta}}{\partial x'^{\beta}} X_{\gamma\delta}$

Mixed tensor $X'^{\alpha}_{\beta\gamma} = \frac{\partial x'^{\alpha}}{\partial x^{\delta}} \frac{\partial x^{\varepsilon}}{\partial x'^{\beta}} \frac{\partial x^{\mu}}{\partial x'^{\gamma}} X^{\delta}_{\varepsilon\mu}$

How does a basis vector change in the direction of another basis vector?

$$\nabla_{e_j} e_i = \Gamma_{ij}^k e_k$$

For general vectors and directions

$$\begin{aligned} \nabla_v w &= \nabla_{v^j e_j} (w^i e_i) = v^j \nabla_{e_j} (w^i e_i) = v^j w^i \nabla_{e_j} e_i + v^j e_i \nabla_{e_j} w^i \\ &= v^j w^i \Gamma_{ij}^k e_k + v^j \frac{\partial w^i}{\partial x^j} e_i = \left(v^j w^i \Gamma_{ij}^k + v^j \frac{\partial w^k}{\partial x^j} \right) e_k \end{aligned}$$

And for a tensor with generic indices

$$\begin{aligned} (\nabla_{e_c} T)_{b_1 \dots b_r}^{a_1 \dots a_r} &= \frac{\partial \nabla_{e_c} T_{b_1 \dots b_r}^{a_1 \dots a_r}}{\partial x^c} \\ &+ \Gamma_{dc}^{a_1} T_{b_1 \dots b_r}^{da_2 \dots a_r} + \dots + \Gamma_{dc}^{a_r} T_{b_1 \dots b_r}^{a_1 \dots a_{r-1} d} \\ &- \Gamma_{b_1 c}^d T_{db_2 \dots b_r}^{a_1 \dots a_r} - \dots - \Gamma_{b_s c}^d T_{b_1 \dots b_{s-1} d}^{a_1 \dots a_r} \end{aligned}$$

Metric compatibility condition: $\nabla_{\rho} g_{\mu\nu} = 0$

implies cycling the indices:

$$\nabla_{\rho} g_{\mu\nu} = \partial_{\rho} g_{\mu\nu} - \Gamma_{\rho\nu}^{\lambda} g_{\lambda\mu} - \Gamma_{\rho\mu}^{\lambda} g_{\lambda\nu} = 0$$

$$\nabla_{\mu} g_{\nu\rho} = \partial_{\mu} g_{\nu\rho} - \Gamma_{\mu\nu}^{\lambda} g_{\lambda\rho} - \Gamma_{\mu\rho}^{\lambda} g_{\lambda\nu} = 0$$

$$\nabla_{\nu} g_{\rho\mu} = \partial_{\nu} g_{\rho\mu} - \Gamma_{\nu\rho}^{\lambda} g_{\lambda\mu} - \Gamma_{\nu\mu}^{\lambda} g_{\lambda\rho} = 0$$

and summing to zero: $\nabla_{\rho} g_{\mu\nu} - \nabla_{\mu} g_{\nu\rho} - \nabla_{\nu} g_{\rho\mu} = 0$

we have $\partial_{\rho} g_{\mu\nu} - \partial_{\mu} g_{\nu\rho} - \partial_{\nu} g_{\rho\mu} + 2\Gamma_{\mu\nu}^{\lambda} g_{\lambda\rho} = 0$

and solving for Gamma multiplying by the metric tensor

$$\Gamma_{\mu\nu}^{\sigma} = \frac{1}{2} g^{\sigma\rho} (\partial_{\mu} g_{\nu\rho} + \partial_{\nu} g_{\rho\mu} - \partial_{\rho} g_{\mu\nu})$$

Characterization of a geodesic: the change while transported along its own direction must be zero:

$$\nabla_{T^\mu} T^\nu = T^\mu \nabla_\mu T^\nu = 0$$

Writing the covariant derivative:

$$\frac{dT^\mu}{dt} + \Gamma_{\alpha\beta}^\mu T^\alpha T^\beta = 0$$

Introducing coordinates and a parameterized curve:

$$\frac{d^2 x^\mu}{dt^2} + \Gamma_{\alpha\beta}^\mu \frac{dx^\alpha}{dt} \frac{dx^\beta}{dt} = 0$$

Squared curve length $L = \int_{t_1}^{t_2} g_{ij} \dot{x}^i \dot{x}^j dt$

Variation: $\delta L = \int_{t_1}^{t_2} \left(\delta g_{ij} \dot{x}^i \dot{x}^j + 2g_{ij} \delta(\dot{x}^i) \dot{x}^j \right) dt = 0$

$$\delta L = \int_{t_1}^{t_2} \left(\frac{\partial g_{ij}}{\partial x^k} \dot{x}^i \dot{x}^j \delta x^k + 2g_{ij} \dot{x}^i \frac{d}{dt} \delta x^j \right) dt =$$

$$\int_{t_1}^{t_2} \left(\frac{\partial g_{ij}}{\partial x^k} \dot{x}^i \dot{x}^j - 2 \frac{d}{dt} [g_{ij} \dot{x}^i] \right) \delta x^k dt + g_{ij} \frac{dx^i}{dt} \delta x^j \Big|_{t_1}^{t_2} = 0$$

$$= \left(\frac{\partial g_{ij}}{\partial x^k} - 2 \frac{\partial g_{ij}}{\partial x^k} \right) \dot{x}^i \dot{x}^j - 2g_{ij} \frac{d^2 x^i}{dt^2}$$

$$= \frac{d^2 x^k}{dt^2} + \frac{1}{2} g^{kl} \left(\frac{\partial g_{il}}{\partial x^j} + \frac{\partial g_{il}}{\partial x^i} - \frac{\partial g_{ij}}{\partial x^l} \right) \dot{x}^i \dot{x}^j$$

$$= \frac{d^2 x^k}{dt^2} + \frac{1}{2} g^{kl} \Gamma_{ij}^k \dot{x}^i \dot{x}^j = 0$$

Parallel Transport along a closed path

$$V^\mu(BC) = - \int_a^{a+\delta a} d\theta V^\beta \Gamma_{\theta\beta}^\mu |_{\phi=b+\delta b}$$

$$V^\mu(AB) = - \int_b^{b+\delta b} d\phi V^\beta \Gamma_{\phi\beta}^\mu |_{\theta=a}$$

$$V^\mu(CD) = - \int_{b+\delta b}^b d\phi V^\beta \Gamma_{\phi\beta}^\mu |_{\theta=a+\delta a}$$

$$V^\mu(DA) = - \int_{a+\delta a}^a d\theta V^\beta \Gamma_{\theta\beta}^\mu |_{\phi=b}$$

The diagram shows a shaded rectangle in the (θ, ϕ) plane. The vertices are labeled A, B, C, and D. The horizontal axis is θ and the vertical axis is ϕ . The path is traversed counter-clockwise: A to B (up), B to C (right), C to D (down), and D to A (left). The coordinates at each vertex are:

- A: $\theta = a, \phi = b$
- B: $\theta = a, \phi = b + \delta b$
- C: $\theta = a + \delta a, \phi = b + \delta b$
- D: $\theta = a + \delta a, \phi = b$

$$\begin{aligned}
\Delta V^\mu &= \int_b^{b+\delta b} d\phi \left[V^\beta \Gamma_{\phi\beta}^\mu |_{\theta=a+\delta a} - V^\beta \Gamma_{\phi\beta}^\mu |_{\theta=a} \right] \\
&\quad - \int_a^{a+\delta a} d\theta \left[V^\beta \Gamma_{\theta\beta}^\mu |_{\phi=b+\delta b} - V^\beta \Gamma_{\theta\beta}^\mu |_{\phi=b} \right] \\
&= - \left[\int_a^{a+\delta a} d\theta \delta b \frac{\partial}{\partial \phi} \left(V^\beta \Gamma_{\theta\beta}^\mu \right) \int_b^{b+\delta b} d\phi \delta a \frac{\partial}{\partial \theta} \left(V^\beta \Gamma_{\phi\beta}^\mu \right) \right] \\
&= -\delta a \delta b \left[\frac{\partial}{\partial \phi} V^\beta \Gamma_{\theta\beta}^\mu - \frac{\partial}{\partial \theta} V^\beta \Gamma_{\phi\beta}^\mu \right]
\end{aligned}$$

The vector is parallel along one side:

$$\nabla_i V^\mu = \frac{\partial V^\mu}{\partial x^i} + \Gamma_{i\beta}^\mu = \vec{0}$$

Using the definition of partial derivative

$$\begin{aligned}
\Delta V^\mu &= -\delta A \left(\frac{\partial V^\beta}{\partial \phi} \Gamma_{\theta\beta}^\mu + V^\beta \frac{\partial \Gamma_{\theta\beta}^\mu}{\partial \phi} - \frac{\partial V^\beta}{\partial \theta} \Gamma_{\phi\beta}^\mu - V^\beta \frac{\partial \Gamma_{\phi\beta}^\mu}{\partial \theta} \right) \\
&= -\delta A \left(-V^\nu \Gamma_{\phi\nu}^\beta \Gamma_{\theta\beta}^\mu + V^\beta \frac{\partial \Gamma_{\theta\beta}^\mu}{\partial \phi} + V^\nu \Gamma_{\theta\nu}^\beta \Gamma_{\phi\beta}^\mu - V^\beta \frac{\partial \Gamma_{\phi\beta}^\mu}{\partial \theta} \right) \\
&= \delta A V^\beta \left(\Gamma_{\phi\beta}^\nu \Gamma_{\theta\nu}^\mu - \frac{\partial \Gamma_{\theta\beta}^\mu}{\partial \phi} - \Gamma_{\theta\beta}^\nu \Gamma_{\phi\nu}^\mu + \frac{\partial \Gamma_{\phi\beta}^\mu}{\partial \theta} \right)
\end{aligned}$$

$$R_{\beta\gamma\lambda}^\mu = \Gamma_{\lambda\beta}^\nu \Gamma_{\gamma\nu}^\mu - \frac{\partial \Gamma_{\gamma\beta}^\mu}{\partial x^\lambda} - \Gamma_{\gamma\beta}^\nu \Gamma_{\lambda\nu}^\mu + \frac{\partial \Gamma_{\lambda\beta}^\mu}{\partial x^\gamma}$$

Another characterization of the Riemann tensor (cov. deriv. commutator):

$$\nabla_c \nabla_b V_a - \nabla_b \nabla_c V_a = [\nabla_c, \nabla_b] V_a = R_{abc}^d V_d$$

$$R_{abcd} = -R_{bacd} = -R_{abdc} = R_{badc} \quad (\text{symmetry})$$

$$R_{abcd} + R_{adbc} + R_{acdb} = 0 \quad (\text{antisymmetry})$$

$$R_{abcd} + R_{adbc} + R_{acdb} = 0 \quad (\text{cyclicity})$$

Bianchi Identities:

$$\nabla_e R_{abcd} + \nabla_d R_{abec} + \nabla_c R_{abde} = 0$$

$$\nabla_e R_{bd} + \nabla_d R_{be} + \nabla_c R_{bde}^c = 0$$

Einstein Tensor:

$$\nabla_b \left(R_e^b - \frac{1}{2} \delta_e^b R \right) = \nabla_b G_e^b = 0$$

The Riemann tensor is unique in the following sense:

it is the only tensor which can be constructed using only the metric tensor and its first and second derivatives (and it is linear in the second derivatives).

Ist Deutschland flach ?

A= Muenchen

B= Bremen

C = Rostock

D= Dresden

AB = 584 km

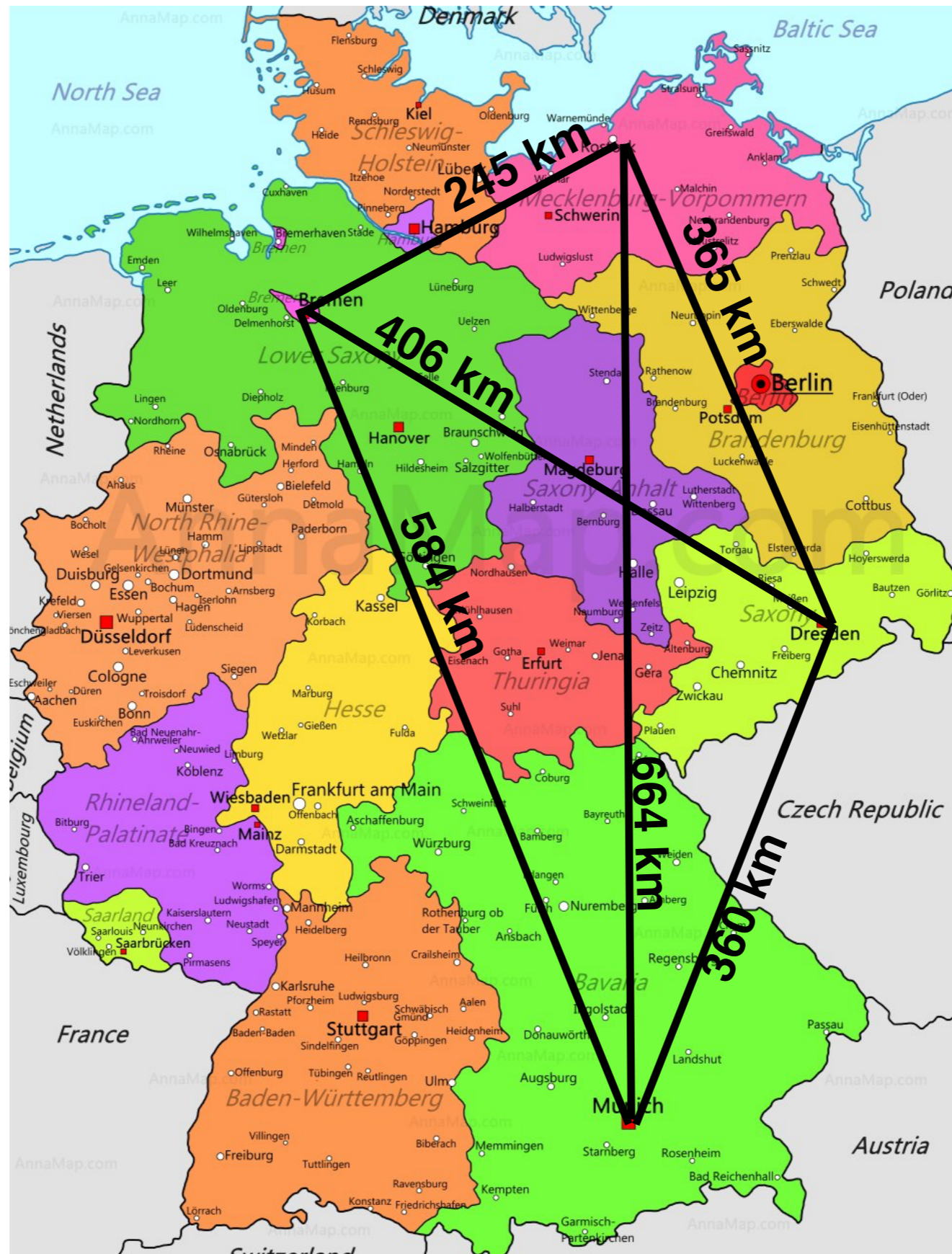
AC = 664 km

AD = 360 km

BC = 245 km

BD = 406 km

CD = 365 km



Exercise: Try to calculate AC with the available data and confront with AC=664 km

Ist Deutschland flach ?

A more elegant way:

calculate the volume of the tetrahedron in 3D space

$$V^2 = \frac{1}{288} \det \begin{pmatrix} 0 & 1 & 1 & 1 & 1 \\ 1 & 0 & \bar{AB}^2 & \bar{AC}^2 & \bar{AD}^2 \\ 1 & \bar{AB}^2 & 0 & \bar{BC}^2 & \bar{BD}^2 \\ 1 & \bar{AC}^2 & \bar{BC}^2 & 0 & \bar{CD}^2 \\ 1 & \bar{AD}^2 & \bar{BD}^2 & \bar{CD}^2 & 0 \end{pmatrix}$$

with the Cayley-Menger determinant.

If the determinant vanishes, the tetrahedron "collapses" on a plane
→ condition for the 4 points to lie on a plane (can you explain why?).

If Germany is not flat, how could you estimate the curvature radius?

For a crude estimate, you can gather some ideas from
<https://en.wikipedia.org/wiki/Horizon>

For a better calculation, use spherical trigonometry.